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# Universal features of correlated bursty behaviour

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Inhomogeneous temporal processes, like those appearing in human communications, neuron spike trains, and seismic signals, consist of high-activity bursty intervals alternating with long low-activity periods. In recent studies such bursty behavior has been characterized by a fat-tailed inter-event time distribution, while temporal correlations were measured by the autocorrelation function. However, these characteristic functions are not capable to fully characterize temporally correlated heterogenous behavior. Here we show that the distribution of the number of events in a bursty period serves as a good indicator of the dependencies, leading to the universal observation of power-law distribution for a broad class of phenomena. We find that the correlations in these quite different systems can be commonly interpreted by memory effects and described by a simple phenomenological model, which displays temporal behavior qualitatively similar to that in real systems.

n nature there are various phenomena, from earthquakes<sup>1</sup> to sunspots<sup>2</sup> and neuronal activity<sup>3</sup>, that show temporally inhomogeneous sequence of events, in which the overall dynamics is determined by aggregate effects of competing processes. This happens also in human dynamics as a result of individual decision making and of various kinds of correlations with one's social environment. These systems can be characterized by intermittent switching between periods of low activity and high activity bursts<sup>4–6</sup>, which can appear as a collective phenomenon similar to processes seen in self-organized criticality<sup>7–16</sup>. In contrast with such self-organized patterns intermittent switching can be detected at the individual level as well (see Fig. 1), seen for single neuron firings or for earthquakes at a single location<sup>17–21</sup> where the famous Omori's law<sup>22,23</sup> describes the temporal decay of aftershock rates at a given spot.

Further examples of bursty behavior at the individual level have been observed in the digital records of human communication activities through different channels<sup>4,24–28</sup>. Over the last few years different explanations have been proposed about the origin of inhomogeneous human dynamics<sup>4,24,29</sup>, including the single event level<sup>30</sup>, and about the impact of circadian and weekly fluctuations<sup>31</sup>. Moreover, by using novel technology of Radio Frequency ID's, heterogeneous temporal behavior was observed in the dynamics of face-to-face interactions<sup>32,33</sup>. This was explained by a reinforcement dynamics<sup>34,35</sup> driving the decision making process at the single entity level.

For systems with discrete event dynamics it is usual to characterize the observed temporal inhomogeneities by the inter-event time distributions,  $P(t_{ie})$ , where  $t_{ie} = t_{i+1} - t_i$  denotes the time between consecutive events. A broad  $P(t_{ie})^{3,25,36}$  reflects large variability in the inter-event times and denotes heterogeneous temporal behavior. Note that  $P(t_{ie})$  alone tells nothing about the presence of correlations, usually characterized by the autocorrelation function,  $A(\tau)$ , or by the power spectrum density. However, for temporally heterogeneous signals of independent events with fat-tailed  $P(t_{ie})$  the Hurst exponent can assign false positive correlations<sup>37</sup> together with the autocorrelation function (see Supplementary Information). To understand the mechanisms behind these phenomena, it is important to know whether there are true correlations in these systems. Hence for systems showing fat-tailed inter-event time distributions, there is a need to develop new measures that are sensitive to correlations but insensitive to fat tails.

In this paper we define a new measure that is capable of detecting whether temporal correlations are present, even in the case of heterogeneous signals. By analyzing the empirical datasets of human communication, earthquake activity, and neuron spike trains, we observe universal features induced by temporal correlations. In the analysis we establish a close relationship between the observed correlations and memory effects and propose a phenomenological model that implements memory driven correlated behavior.



Figure 1 | Activity of single entities with color-coded inter-event times. (a): Sequence of earthquakes with magnitude larger than two at a single location (South of Chishima Island, 8th–9th October 1994) (b): Firing sequence of a single neuron (from rat's hippocampal) (c): Outgoing mobile phone call sequence of an individual. Shorter the time between the consecutive events darker the color.

#### Results

**Correlated events.** A sequence of discrete temporal events can be interpreted as a time-dependent point process, X(t), where  $X(t_i) = 1$  at each time step  $t_i$  when an event takes place, otherwise  $X(t_i) = 0$ . To detect bursty clusters in this binary event sequence we have to identify those events we consider correlated. The smallest temporal scale at which correlations can emerge in the dynamics is between consecutive events. If only X(t) is known, we can assume two consecutive actions at  $t_i$  and  $t_{i+1}$  to be related if they follow each other within a short time interval,  $t_{i+1}-t_i \leq \Delta t^{30.38}$ . For events with the duration  $d_i$  this condition is slightly modified:  $t_{i+1}-(t_i+d_i) \leq \Delta t$ .

This definition allows us to detect bursty periods, defined as a sequence of events where each event follows the previous one within a time interval  $\Delta t$ . By counting the number of events, *E*, that belong to the same bursty period, we can calculate their distribution *P*(*E*) in a signal. For a sequence of independent events, *P*(*E*) is uniquely determined by the inter-event time distribution *P*( $t_{ie}$ ) as follows:

$$P(E=n) = \left(\int_0^{\Delta t} P(t_{ie}) dt_{ie}\right)^{n-1} \left(1 - \int_0^{\Delta t} P(t_{ie}) dt_{ie}\right)$$
(1)

for n > 0. Here the integral  $\int_0^{\Delta t} P(t_{ie}) dt_{ie}$  defines the probability to draw an inter-event time  $P(t_{ie}) \leq \Delta t$  randomly from an arbitrary distribution  $P(t_{ie})$ . The first term of (1) gives the probability that we do it independently n-1 consecutive times, while the second term assigns that the  $n^{th}$  drawing gives a  $P(t_{ie}) > \Delta t$  therefore the evolving train size becomes exactly E = n. If the measured time window is finite (which is always the case here), the integral  $\int_0^{\Delta t} P(t_{ie}) dt_{ie} = a$ where a < 1 and the asymptotic behaviour appears like  $P(E = n) \sim a^{(n-1)}$  in a general exponential form (for related numerical results see SI). Consequently for any finite independent event sequence the P(E)distribution decays exponentially even if the inter-event time distribution is fat-tailed. Deviations from this exponential behavior indicate correlations in the timing of the consecutive events.

**Bursty sequences in human communication.** To check the scaling behavior of P(E) in real systems we focused on outgoing events of individuals in three selected datasets: (a) A mobile-call dataset from a European operator; (b) Text message records from the same dataset; (c) Email communication sequences<sup>26</sup> (for detailed data description see Methods). For each of these event sequences the distribution of inter-event times measured between outgoing events are shown in Fig. 2 (left bottom panels) and the estimated power-law exponent values are summarized in Table 1. To explore the scaling behavior of the autocorrelation function, we took the averages over 1,000

randomly selected users with maximum time lag of  $\tau = 10^6$ . In Fig. 2.a and b (right bottom panels) for mobile communication sequences strong temporal correlation can be observed (for exponents see Table 1). The power-law behavior in  $A(\tau)$  appears after a short period denoting the reaction time through the corresponding channel and lasts up to 12 hours, capturing the natural rhythm of human activities. For emails in Fig. 2.c (right bottom panels) long term correlation are detected up to 8 hours, which reflects a typical office hour rhythm (note that the dataset includes internal email communication of a university staff).

The broad shape of  $P(t_{ie})$  and  $A(\tau)$  functions confirm that human communication dynamics is inhomogeneous and displays nontrivial correlations up to finite time scales. However, after destroying event-event correlations by shuffling inter-event times in the sequences (see Methods) the autocorrelation functions still show slow power-law like decay (empty symbols on bottom right panels), indicating spurious unexpected dependencies. This clearly demonstrates the disability of  $A(\tau)$  to characterize correlations for heterogeneous signals (for further results see SI). However, a more effective measure of such correlations is provided by P(E). Calculating this distribution for various  $\Delta t$  windows, we find that the P(E) shows the following scale invariant behavior

$$P(E) \sim E^{-\beta} \tag{2}$$

for each of the event sequences as depicted in the main panels of Fig. 2. Consequently P(E) captures strong temporal correlations in the empirical sequences and it is remarkably different from P(E) calculated for independent events, which, as predicted by (1), show exponential decay (empty symbols on the main panels).

Exponential behavior of P(E) was also expected from results published in the literature assuming human communication behavior to be uncorrelated<sup>29,30,39</sup>. However, the observed scaling behavior of P(E) offers direct evidence of correlations in human dynamics, which can be responsible for the heterogeneous temporal behavior. These correlations induce long bursty trains in the event sequence rather than short bursts of independent events.

We have found that the scaling of the P(E) distribution is quite robust against changes in  $\Delta t$  for an extended regime of time-window sizes (Fig. 2). In addition, the measurements performed on the mobile-call sequences indicate that the P(E) distribution remains fat-tailed also when it is calculated for users grouped by their activity. Moreover, the observed scaling behavior of the characteristic functions remains similar if we remove daily fluctuations (for results see SI). These analyses together show that the detected correlated behavior is not an artifact of the averaging method nor can be attributed to variations in activity levels or circadian fluctuations.



Figure 2 | The characteristic functions of human communication event sequences. The P(E) distributions with various  $\Delta t$  time-window sizes (main panels),  $P(t_{ie})$  distributions (left bottom panels) and average autocorrelation functions (right bottom panels) calculated for different communication datasets. (a) Mobile-call dataset: the scale-invariant behavior was characterized by power-law functions with exponent values  $\alpha \simeq 0.5$ ,  $\beta \simeq 4.1$  and  $\gamma \simeq 0.7$  (b) Almost the same exponents were estimated for short message sequences taking values  $\alpha \simeq 0.6$ ,  $\beta \simeq 3.9$  and  $\gamma \simeq 0.7$ . (c) Email event sequence with estimated exponents  $\alpha \simeq 0.75$ ,  $\beta \simeq 2.5$  and  $\gamma \simeq 1.0$ . A gap in the tail of  $A(\tau)$  on figure (c) appears due to logarithmic binning and slightly negative correlation values. Empty symbols assign the corresponding calculation results on independent sequences. Lanes labeled with s, m, h and d are denoting seconds, minutes, hours and days respectively.

Bursty periods in natural phenomena. As discussed above, temporal inhomogeneities are present in the dynamics of several natural phenomena, e.g. in recurrent seismic activities at the same location<sup>19,20,21</sup> (for details see Methods and SI). The broad distribution of inter-earthquake times in Fig. 3.a (right top panel) demonstrates the temporal inhomogeneities. The characterizing exponent value  $\gamma$ = 0.7 is in qualitative agreement with the results in the literature<sup>23</sup> as  $\gamma = 2 - 1/p$  where p is the Omori decay exponent<sup>22,23</sup>. At the same time the long tail of the autocorrelation function (right bottom panel) assigning long-range temporal correlations. Counting the number of earthquakes belonging to the same bursty period with  $\Delta t$  = 2...32 hours window sizes, we obtain a broad P(E) distribution (see Fig. 3.a main panel), as observed earlier in communication sequences, but with a different exponent value  $\beta = 2.5$  (see in Table 1). This exponent value meets with known seismic properties as it can be derived as  $\beta = b/a + 1$ , where *a* denotes the productivity law exponent<sup>40</sup>, while b is coming from the well known Gutenberg-Richter law<sup>41</sup>. Note that the presence of long bursty trains in earthquake sequences were already assigned to long temporal correlations by measurements using conditional probabilities<sup>42,43</sup>.

Another example of naturally occurring bursty behavior is provided by the firing patterns of single neurons (see Methods). The

Table 1 | Characteristic exponents of the ( $\alpha$ ) autocorrelation function, ( $\beta$ ) bursty number, ( $\gamma$ ) inter-event time distribution functions and  $\nu$  memory functions calculated in different datasets (see SI) and for the model study

	α	β	γ	v
Mobile-call sequence	0.5	4.1	0.7	3.0
Short message sequence	0.6	3.9	0.7	2.8
Email sequence	0.75	2.5	1.0	1.3
Earthquake sequence (Japan)	0.3	2.5	0.7	1.6
Neuron firing sequence	1.0	2.3	1.1	1.3
Model	0.7	3.0	1.3	2.0

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recorded neural spike sequences display correlated and strongly inhomogeneous temporal bursty behavior, as shown in Fig. 3.b. The distributions of the length of neural spike trains are found to be fat-tailed and indicate the presence of correlations between consecutive bursty spikes of the same neuron.

**Memory process.** In each studied system (communication of individuals, earthquakes at given location, or neurons) qualitatively similar behaviour was detected as the single entities performed low frequency random events or they passed through longer correlated bursty cascades. While these phenomena are very different in nature, there could be some element of similarities in their mechanisms. We think that this common feature is a threshold mechanism.

From this point of view the case of human communication data seems problematic. In fact generally no accumulation of stress is needed for an individual to make a phone call. However, according to the Decision Field Theory of psychology<sup>44</sup>, each decision (including initiation of communication) is a threshold phenomenon, as the stimulus of an action has to reach a given level for to be chosen from the enormously large number of possible actions.

As for earthquakes and neuron firings it is well known that they are threshold phenomena. For earthquakes the bursty periods at a given location are related to the relaxation of accumulated stress after reaching a threshold<sup>7-9</sup>. In case of neurons, the firings take place in bursty spike trains when the neuron receives excitatory input and its membrane potential exceeds a given potential threshold<sup>45</sup>. The spikes fired in a single train are correlated since they are the result of the same excitation and their firing frequency is coding the amplitude of the incoming stimuli<sup>46</sup>.

The correlations taking place between consecutive bursty events can be interpreted as a memory process, allowing us to calculate the probability that the entity will perform one more event within a  $\Delta t$ time frame after it executed *n* events previously in the actual cascade. This probability can be written as:





Figure 3 | The characteristic functions of event sequences of natural phenomena. The P(E) distributions of correlated event numbers with various  $\Delta t$  time-window sizes (main panels),  $P(t_{ie})$  distributions (right top panels) and average autocorrelation functions (right bottom panels). (a) One station records of Japanese earthquake sequences from 1985 to 1998. The functional behavior is characterized by the fitted power-law functions with corresponding exponents  $\alpha \simeq 0.3$ ,  $\beta \simeq 2.5$  and  $\gamma \simeq 0.7$ . Inter-event times for  $P(t_{ie})$  were counted with 10 second resolution. (b) Firing sequences of single neurons with 2 millisecond resolution. The corresponding exponents take values as  $\alpha \simeq 1.0$ ,  $\beta \simeq 2.3$  and  $\gamma \simeq 1.1$ . Empty symbols assign the calculation results on independent sequences. Lanes labeled with ms, s, m, h, d and w are denoting milliseconds, seconds, minutes, hours, days and weeks respectively.

$$p(n) = \frac{\sum_{E=n+1}^{\infty} P(E)}{\sum_{E=n}^{\infty} P(E)}.$$
(3)

Therefore the memory function, p(n), gives a different representation of the distribution P(E). The p(n) calculated for the mobile call sequence are shown in Fig. 4.a for trains detected with different window sizes. Note that in empirical sequences for trains with size smaller than the longest train, it is possible to have p(n) = 1 since the corresponding probability would be P(E = n) = 0. At the same time due to the finite size of the data sequence the length of the longest bursty train is limited such that p(n) shows a finite cutoff.

We can use the memory function to simulate a sequence of correlated events. If the simulated sequence satisfies the scaling condition in (2) we can derive the corresponding memory function by substituting (2) into (3), leading to:

$$p(n) = \left(\frac{n}{n+1}\right)^{\nu} \tag{4}$$

with the scaling relation (see SI):

$$\beta = \nu + 1. \tag{5}$$

In order to check whether (5) holds for real systems and whether the memory function in (4) describes correctly the memory in real processes we compare it to a memory function extracted from an empirical P(E) distributions. We selected the P(E) distribution of the mobile call dataset with  $\Delta t = 600$  second and derived the corresponding p(n) function. The complement of the memory function, 1-p(n), is presented in Fig. 4.b where we show the original function with strong finite size effects (grey dots) and the same function after logarithmic binning (black dots).

Taking equation (4) we fit the theoretical memory function to the log-binned empirical results using least-squares method with only one free parameter, v. We find that the best fit offers an excellent agreement with the empirical data (see Fig. 4.b and also Fig. 4.a) with  $v = 2.971 \pm 0.072$ . This would indicate  $\beta \simeq 3.971$  through (5), close to the approximated value  $\beta \simeq 4.1$ , obtained from directly fitting the empirical *P*(*E*) distributions in the main panel of Fig. 2.a (for fits of other datasets see SI). In order to validate whether our approximation is correct we take the theoretical memory function p(n) of the form (4) with parameter v = 2.971 and generate bursty trains of  $10^8$  events. As shown in Fig. 5.c, the scaling of the *P*(*E*) distribution obtained for the simulated event trains is similar to the empirical function, demonstrating the validity of the chosen analytical form for the memory function.

**Model study.** As the systems we analysed are of quite different nature, from physics (earthquakes) to social (human communication) and biological (neuron spikes) systems, finding a single mechanistic model to describe them all is impossible. Therefore, our goal is not to reproduce in detail our observations for the different systems but to identify minimal conditions or common characteristics that may play a role in all of their dynamics and are sufficient to reproduce the observed overall temporal behaviour. Here we define a phenomenological model which integrates the deliberated features and study how they are related to each other.

Reinforcement dynamics with memory. We assume that the investigated systems can be described with a two-state model, where an entity can be in a normal state A, executing independent events with longer inter-event times, or in an excited state B, performing correlated events with higher frequency, corresponding to the observed bursts. To induce the inter-event times between the consecutive events we apply a reinforcement process based on the assumption that the longer the system waits after an event, the larger the probability that it will keep waiting. Such dynamics shows strongly heterogeneous temporal features as discussed in<sup>34,35</sup>. For our two-state model system we define a process, where the generation of the actual inter-event time depends on the current state of the system. The inter-event times are induced by the reinforcement functions that give the probability to wait one time unit longer after the system has waited already time  $t_{ie}$  since the last event. These functions are defined as

$$f_{A,B}(t_{ie}) = \left(\frac{t_{ie}}{t_{ie}+1}\right)^{\mu_{A,B}} \tag{6}$$

where  $\mu_A$  and  $\mu_B$  control the reinforcement dynamics in state A and B, respectively. These functions follow the same form as the previously defined memory function in (4) and satisfy the corresponding scaling relation in (5). If  $\mu_A \ll \mu_B$  the characteristic inter-event times at state A and B become fairly different, which induces further temporal inhomogeneities in the dynamics. The



Figure 4 | Empirical and fitted memory functions of the mobile call sequence (a) Memory function calculated from the mobile call sequence using different  $\Delta t$  time windows. (b) 1-p(n) complement of the memory function measured from the mobile call sequence with  $\Delta t = 600$  second and fitted with the analytical curve defined in equation (4) with v = 2.971. Grey symbols are the original points, while black symbols denotes the same function after logarithmic binning. (c) P(E) distributions measured in real and in modeled event sequences.

actual state of the system is determined by transition probabilities shown in Fig. 5.b, where to introduce correlations between consecutive excited events performed in state B we utilize the memory function defined in equation (4).

To be specific, the model is defined as follows: first the system performs an event in a randomly chosen initial state. If the last event was in the normal state A, it waits for a time induced by  $f_A(t_{ie})$ , after which it switches to excited state B with probability  $\pi$  and performs an event in the excited state, or with probability  $1-\pi$  stays in the normal state A and executes a new normal event. In the excited state the inter-event time for the actual event comes from  $f_B(t_{ie})$  after which the system decides to execute one more excited event in state B with a probability p(n) that depends on the number n of excited



Figure 5 | Schematic definition and numerical results of the model study. (a) P(E) distributions of the synthetic sequence after logarithmic binning with window sizes  $\Delta t = 1...1024$ . The fitted power-law function has an exponent  $\beta = 3.0$ . (b) Transition probabilities of the reinforcement model with memory. (c) Logarithmic binned inter-event time distribution of the simulated process with a maximum interevent time  $t_{ie}^{max} = 10^6$ . The corresponding exponent value is  $\gamma = 1.3$ . (d) The average logarithmic binned autocorrelation function with a maximum lag  $\tau^{max} = 10^4$ . The function can be characterized by an exponent  $\alpha = 0.7$ . Simulation results averaged over 1000 independent realizations with parameters  $\mu_A = 0.3$ ,  $\mu_B = 5.0$ ,  $\nu = 2.0$ ,  $\pi = 0.1$  and  $T = 10^9$ . For the calculation we chose the maximum inter-event time  $t_{ie}^{max} = 10^5$ , which is large enough not to influence short temporal behavior, but it increases the program performance considerably.

events since the last event in normal state. Otherwise it switches back to a normal state with probability 1-p(n). Note that a similar model without memory was already defined in the literature<sup>47</sup>.

The numerical results predicted by the model are summarized in Fig. 5 and Table 1. We find that the inter-event time distribution in Fig. 5.c reflects strong inhomogeneities as it takes the form of a scalefree function with an exponent value  $\gamma = 1.3$ , satisfying the relation  $\gamma$  $= \mu_A + 1$ . As a result of the heterogeneous temporal behavior with memory involved, we detected spontaneously evolving long temporal correlations as the autocorrelation function shows a powerlaw decay. Its exponent  $\alpha = 0.7$  (see Fig. 5.d) also satisfies the relation  $\alpha + \gamma = 2$  (see SI). The *P*(*E*) distribution also shows fat-tailed behavior for each investigated window size ranging from  $\Delta t = 1$  to  $2^{10}$  (see Fig. 5.a). The overall signal here is an aggregation of correlated long bursty trains and uncorrelated single events. This explains the weak  $\Delta t$  dependence of P(E) for larger window sizes, where more independent events are merged with events of correlated bursty cascades, which induces deviation of P(E) from the expected scale-free behavior. The *P*(*E*) distributions can be characterized by an exponent  $\beta =$ 3.0 in agreement with the analytical result in (5) and it confirms the presence of correlated bursty cascades. In addition, even if we fix the value of  $\beta$  and  $\gamma$ , the  $\alpha$  exponent satisfies the condition  $\alpha < \gamma < \beta$ , an inequality observed in empirical data (see Table 1).

#### Discussion

In the present study we introduced a new measure, the number of correlated events in bursty cascades, which detects correlations and heterogeneity in temporal sequences. It offers a better characterization of correlated heterogeneous signals, capturing a behavior that cannot be observed from the inter-event time distribution and the autocorrelation function. The discussed strongly heterogeneous dynamics was documented in a wide range of systems, from human dynamics to natural phenomena. The time evolution of these systems were found to be driven by temporal correlations that induced scaleinvariant distributions of the burst lengths. This scale-free feature holds for each studied system and can be characterized by different system-dependent exponents, indicating a new universal property of correlated temporal patterns emerging in complex systems.

We found that the bursty trains can be explained in terms of memory effects, which can account for the heterogeneous temporal behavior. In order to better understand the dynamics of temporally correlated bursty processes at single entity level we introduced a phenomenological model that captures the common features of the investigated empirical systems and helps us understand the role they play during the temporal evolution of heterogeneous processes.



#### **Methods**

Data processing. To study correlated human behavior we selected three datasets containing time-stamped records of communication through different channels for a large number of individuals. For each user we extract the sequence of outgoing events as we are interested in the correlated behavior of single entities. The datasets we have used are as follows: (a) A mobile-call dataset from a European operator covering  $\sim$ 325 $\times$ 10<sup>6</sup> million voice call records of  $\sim$ 6.5 $\times$ 10<sup>6</sup> users during 120 days<sup>48</sup>. (b) Text message records from the same dataset consisting of 125.5  $\times$  10  $^{6}$  events between the same number of users. Note that to consider only trusted social relations these events were executed between users who mutually called each other at least one time during the examined period. Consecutive text messages of the same user with waiting times smaller than 10 seconds were considered as a single multipart message<sup>49</sup> though the  $P(t_{ie})$  and  $A(\tau)$  functions do not take values smaller than 10 seconds in Fig. 2.b. (c) Email communication sequences of 2, 997 individuals including  $20.2 \times 10^4$  events during 83 days<sup>26</sup>. From the email sequence the multicast emails (consecutive emails sent by the same user to many other with inter-event time 0) were removed in order to study temporally separated communication events of individuals. To study earthquake sequences we used a catalog that includes all earthquake events in Japan with magnitude larger than two between 1st July 1985 and 31st December 1998<sup>50</sup>. We considered each recorded earthquake as a unique event regardless whether it was a main-shock or an after-shock. For the single station measurement we collected a time order list of earthquakes with epicenters detected at the same region  $^{7,21}$  (for other event collection methods see SI). The resulting data consists of 198, 914 events at 238 different regions. The utilized neuron firing sequences consist of 31, 934 outgoing firing events of 1, 052 single neurons which were collected with 2 millisecond resolution from rat's hippocampal slices using fMCI techniques<sup>51,52</sup>.

**Random shuffling of inter-event times of real sequences.** To generate independent event sequences from real data in Fig. 2 and 3 (empty symbols) we randomly shuffled the inter-event times of entities (persons, locations, and neurons) allowing to change  $t_{ie}$  values between any entities but keeping the original event number unchanged for each of them. This way the original inter-event time and node strength distributions remain unchanged but we receive null model sequences where every temporal correlations were destroyed. The aim of this calculation was twofold as to show on real data that the autocorrelation function still scales as a power-law after temporal correlated signals. The presented P(E) distributions were calculated with one  $\Delta t$  window size to demonstrate this behaviour.

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## **Authors contributions**

All authors designed the research and participated in the writing of the manuscript. MK analysed the empirical data and did the numerical calculations. MK and JK completed the corresponding analytical derivations.

## Additional information

Supplementary information accompanies this paper at http://www.nature.com/ scientificreports

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